

Uncertainty Principle

$$\sigma_x = \sqrt{\langle X^2 \rangle - \langle X \rangle^2}$$

$$\sigma_p = \sqrt{\langle p^2 \rangle - \langle p \rangle^2}$$

Heisenberg

$$\sigma_x \sigma_p \geq \frac{\hbar}{2}$$

- If we know the position exactly: $\langle x \rangle$ is well defined and $\sigma_x \rightarrow 0$

$$\sigma_x \sigma_p \geq \frac{\hbar}{2} \Rightarrow \sigma_p \rightarrow \infty$$

If we know very well the position $\langle x \rangle$, then we know very little about the momentum $\langle k \rangle$.

$\phi(k)$: very localized $\rightarrow \psi(x)$ was unlocalized

$\phi(k)$: very delocalized $\rightarrow \psi(x)$ was localized

$$\phi(k) = 1$$

$$\psi(x) = \frac{1}{\sqrt{2\pi}} \delta(x)$$

Demonstration

A, B such $[A, B] = AB - BA \neq 0$ they don't commute

$$\sigma_A^2 = \langle \psi | (A - \langle A \rangle)^2 | \psi \rangle$$

(X)

A and B are observables

$$\langle \psi | (A^2 - A\langle A \rangle - \langle A \rangle A + \langle A \rangle^2) | \psi \rangle$$

$$= \langle \psi | A^2 | \psi \rangle - 2\langle A \rangle \langle A \rangle + \langle A \rangle^2$$

$$= \langle A^2 \rangle - \langle A \rangle^2$$

$$A^\dagger = A$$

$$B^\dagger = B$$

A is hermitian $\rightarrow \langle A \rangle \in \mathbb{R}$

$A - \langle A \rangle$ is also hermitian $\Rightarrow A - \langle A \rangle = (A - \langle A \rangle)^\dagger$

$$\begin{aligned}\sigma_A^2 &= \langle \psi | (A - \langle A \rangle)^2 | \psi \rangle \\ &= \langle \psi | (A - \langle A \rangle) (A - \langle A \rangle) | \psi \rangle \\ &= \langle \psi | (A - \langle A \rangle)^\dagger (A - \langle A \rangle) | \psi \rangle \\ &= \langle \alpha | \alpha \rangle\end{aligned}$$

$$\begin{aligned}|\alpha\rangle &= (A - \langle A \rangle) |\psi\rangle \\ \langle \alpha| &= \langle \psi | (A - \langle A \rangle)^\dagger\end{aligned}$$

$$\sigma_B^2 = \langle \beta | \beta \rangle \quad \text{using} \quad |\beta\rangle = (B - \langle B \rangle) |\psi\rangle$$

$|\alpha\rangle$ and $|\beta\rangle$ are vectors! \Rightarrow vector space
 \rightarrow inner product

$$\langle \alpha | \alpha \rangle = |\alpha|^2$$

$$\vec{u} \cdot \vec{u} = |\vec{u}|^2$$

$$\langle \beta | \beta \rangle = |\beta|^2$$

$$\langle \alpha | \beta \rangle =$$

$$\vec{u} \cdot \vec{v} = |\vec{u}| |\vec{v}| \cos \theta$$

Cauchy-Schwarz inequality

$$\vec{v} \cdot \vec{u} \leq |\vec{u}| |\vec{v}|$$

$$\langle \alpha | \beta \rangle \langle \beta | \alpha \rangle \leq \langle \alpha | \alpha \rangle \langle \beta | \beta \rangle$$

$$\langle \beta | \alpha \rangle = \langle \alpha | \beta \rangle^*$$

$$|\langle \alpha | \beta \rangle|^2 \leq \langle \alpha | \alpha \rangle \langle \beta | \beta \rangle = \sigma_A^2 \sigma_B^2$$

$$\langle \alpha | \beta \rangle = \langle \psi | (A - \langle A \rangle)^\dagger (B - \langle B \rangle) | \psi \rangle$$

$$= \langle \psi | (AB - A\langle B \rangle - \langle A \rangle B + \langle A \rangle \langle B \rangle) | \psi \rangle$$

$$= \langle \psi | AB | \psi \rangle - \langle A \rangle \langle B \rangle - \langle A \rangle \langle B \rangle + \langle A \rangle \langle B \rangle$$

$$= \langle AB \rangle - \langle A \rangle \langle B \rangle$$

$$\langle \beta | \alpha \rangle = \langle \psi | (B - \langle B \rangle)^\dagger (A - \langle A \rangle) | \psi \rangle$$

$$\begin{aligned}
&= \langle \psi | (BA - B \langle A \rangle - \overbrace{A \langle B \rangle}^{\downarrow} + \langle B \rangle \langle A \rangle) | \psi \rangle \\
&= \langle BA \rangle - \langle A \rangle \langle B \rangle - \langle A \rangle \langle B \rangle + \langle A \rangle \langle B \rangle \\
&= \underline{\langle BA \rangle} - \langle A \rangle \langle B \rangle
\end{aligned}$$

Consider $z \in \mathbb{C}$

$$|z|^2 = \text{Re}^2(z) + \text{Im}^2(z) \quad \checkmark$$

$$z = a + ib \quad z^* = a - ib$$

$$\begin{aligned}
|z|^2 = z z^* &= (a + ib)(a - ib) = a^2 - iab + iab + b^2 \\
&= a^2 + b^2
\end{aligned}$$

$$|z|^2 = \underbrace{\text{Re}^2(z)} + \text{Im}^2(z) \geq \underbrace{\text{Im}^2(z)} \quad \text{Re}^2(z) \geq 0$$

$$\text{Im}(z) = \frac{z - z^*}{2i}$$

$$z = \langle \alpha | \beta \rangle$$

$$z^* = \langle \beta | \alpha \rangle$$

$$\frac{z - z^*}{2i} = \frac{1}{2i} (\langle \alpha | \beta \rangle - \langle \beta | \alpha \rangle)$$

$$= \frac{1}{2i} \left[\langle AB \rangle - \langle A \rangle \langle B \rangle - (\langle BA \rangle - \langle A \rangle \langle B \rangle) \right]$$

$$= \frac{1}{2i} \left(\langle AB \rangle - \langle A \rangle \langle B \rangle - \langle BA \rangle + \langle A \rangle \langle B \rangle \right)$$

$$= \frac{1}{2i} (\langle AB \rangle - \langle BA \rangle)$$

$$= \frac{1}{2i} (\langle AB - BA \rangle)$$

$$\langle AB \rangle = \langle \psi | AB | \psi \rangle$$

$$\langle AB - BA \rangle = \langle \psi | (AB - BA) | \psi \rangle$$

$$= \langle AB \rangle - \langle BA \rangle$$

$$\text{Im}(\langle \alpha | \beta \rangle) = \frac{1}{2i} \langle [A, B] \rangle$$

$$\begin{aligned}
\text{Im}^2(\langle \alpha | \beta \rangle) &\leq |\langle \alpha | \beta \rangle|^2 \leq \langle \alpha | \alpha \rangle \langle \beta | \beta \rangle \\
&\leq \sigma_A^2 \sigma_B^2
\end{aligned}$$

$$\text{Im}^2(\langle \alpha | \beta \rangle) \leq \sigma_A^2 \sigma_B^2$$

$$\left(\frac{1}{2i} \langle [A, B] \rangle \right)^2 \leq \sigma_A^2 \sigma_B^2$$

Generalized uncertainty principle, which applies to any pair of operators that do not commute.

$$[\hat{x}, \hat{p}] f(x)$$

$$\hat{p} \rightarrow -i\hbar \partial_x$$

$$= (\hat{x}\hat{p} - \hat{p}\hat{x}) f(x)$$

$$= -i\hbar x \partial_x f(x) - (-i\hbar) \partial_x x f(x)$$

$$= -i\hbar x \partial_x f + i\hbar (f + x \partial_x f)$$

$$= -i\hbar x \partial_x f + i\hbar f + i\hbar x \partial_x f$$

$$= i\hbar f \Rightarrow$$

$$[\hat{x}, \hat{p}] = \underline{i\hbar}$$

$$\langle [x, p] \rangle = i\hbar$$

$$\left(\frac{1}{2i} \langle [x, p] \rangle \right)^2 = \left(\frac{1}{2i} i\hbar \right)^2 = \left(\frac{\hbar}{2} \right)^2 \leq \sigma_x^2 \sigma_p^2$$

$$\frac{\hbar}{2} \leq \sigma_x \sigma_p$$